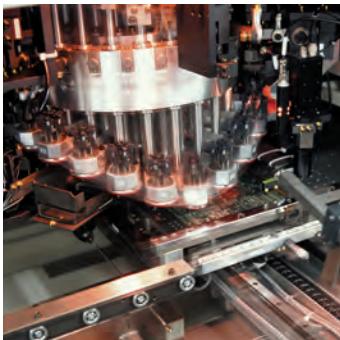


aerospace  
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## Single Cable Servo Drive System

SME Motors and TPD-M Drives with Hiperface DSL® Feedback



ENGINEERING YOUR SUCCESS.

Autoryzowany dystrybutor Parker:

**ARA**  
PNEUMATIK  
53-012 Wrocław tel. 71 364 72 82  
ul. Wyścigowa 38 fax 71 364 72 83  
[www.arapneumatik.pl](http://www.arapneumatik.pl)





#### ***WARNING – USER RESPONSIBILITY***

**FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.**

- This document and other information from Parker-Hannifin Corporation, its subsidiaries and authorized distributors provide product or system options for further investigation by users having technical expertise.
- The user, through its own analysis and testing, is solely responsible for making the final selection of the system and components and assuring that all performance, endurance, maintenance, safety and warning requirements of the application are met. The user must analyze all aspects of the application, follow applicable industry standards, and follow the information concerning the product in the current product catalog and in any other materials provided from Parker or its subsidiaries or authorized distributors.
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## **Single Cable Servo Drive System**

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# Parker Hannifin

## - the global leader in motion and control technologies

### A world class player on a local stage

#### Global Product Design

Parker Hannifin has more than 40 years experience in the design and manufacturing of drives, controls, motors and mechanical products. With dedicated global product development teams, Parker draws on industry-leading technological leadership and experience from engineering teams in Europe, North America and Asia.

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Milan, Italy

##### Asia

Shanghai, China  
Chennai, India

##### North America

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Wadsworth, Ohio  
Charlotte, North Carolina  
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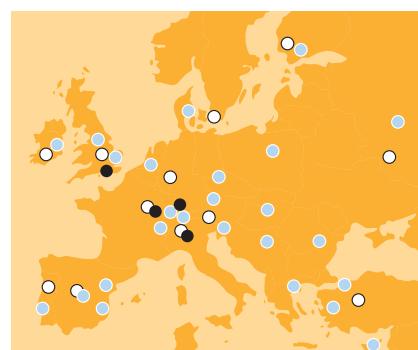
For contact information, please refer to the Sales Offices on the back cover of this document or visit [www.parker.com](http://www.parker.com)



Milan, Italy



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● Manufacturing  
○ Parker Sales Offices  
● Distributors



Dijon, France

# Single Cable Servo Drive System

## SME Motors and TPD-M Drives with Hiperface DSL® feedback

### General Overview

#### Description

The Single Cable Servo Drive System from Parker is a combination of the low inertia servo motor SME and the triple axis servo drive TPD-M based on the Hiperface DSL® digital feedback technology.

The encoder feedback communication is fully integrated into the motor power cable and thus no separate feedback cable between drive and motor is required.

The new feedback system is a purely digital encoder communication protocol with exceptional performance. The absolute position determination, a resolution of up to 20 bit per turn, as well as 4096 maximum rotations, is unique in its class.

The System is completed by the multi-axis servo drive TPD-M which represents one of the most compact solutions on the market giving the possibility of controlling up to three single cable SME servo motors with one 50 mm drive module.

Therefore, the Single Cable Servo Drive System from Parker is a bespoke solution to provide machine builders with lower cabling and installation cost and the possibility to reduce control panel size and machine footprint.

#### Feedback-Features

- One cable connection between drive and motor instead of two
- No need for separate feedback cable and connector
- Fully digital and interference-free communication
- Synchronous, bidirectional, multi-channel
- Easy setup and reduced wiring

#### Applications

- Packaging Machinery
- Material Handling
- Machine Tools
- Robotics
- Paper & Converting



TPD-M triple axis servo drive connected to SME motors via Hiperface DSL® interface: One cable per servo motor instead of two.

#### Technical Characteristics - Overview

##### TPD-M

TPD Axis	Continuos current [A <sub>rms</sub> ]	Peak current A ( $\leq 2$ s)
3 axis	2 + 2 + 2	4 + 4 + 4
	8 + 5 + 5	16 + 10 + 10
2 axis	2 + 2	4 + 4
	5 + 5	10 + 10
	8 + 8	16 + 16
1 axis	5/10/15/30	10/20/30/60

##### SME Single Cable Servo Motors

Motor Type	Permanent magnets synchronous servomotor
Rotor Design	Rotor with surface rare earth magnets
Power Range	0.2...5.3 kW
Torque Range	0.5...17 Nm
Speed Range	0...7500 min <sup>-1</sup>

# Single Cable Servo Drive System

## Traditional vs. Single Cable Servo Drive System Solution

### The difference

The difference between the traditional solution and the latest Single Cable Servo Drive System is immediately obvious and makes this an extremely cost effective and also reliable solution. First notice the simplicity provided by the Single Cable Servo Drive System, due to the fact that the feedback communication is fully integrated into the motor power cable, but then see how complexity and the costs of the system are significantly reduced and the performances increased, due to the following benefits:

### Quick and simple wiring

With less cables and connectors, machine setup is much more straight forward.

### Reduced wiring costs

The opportunity of having a single cable, offers machine builders significative savings on costs for cables and connectors.

### Reliable system

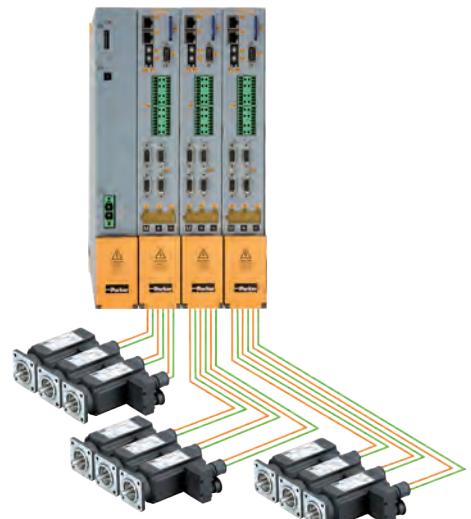
The reduced number of connections reduces the potential points of failure.

### Efficient feedback control

Being fully digital, the performance of the motor feedback is very accurate.



Single Cable Servo Drive Solution



Traditional Solution

# Low Inertia Servo Motors - SME

## Product Overview

### Description

The SME Series of highly-dynamic brushless servo motors have been design to combine the cuttingedge technology of Parker Hannifin products with extremely high performance.

Thanks to the innovative "salient pole" technology, the motor's dimensions are considerably reduced with significant advantages in terms of specific torque, overall dimensions and dynamic performance. Compared to traditional-technology brushless servo motors, the specific torque is approximately 30 % higher, overall dimensions are considerably reduced and, consequently rotor inertias are extremely low. Thanks to the high quality of Neodymium-Iron-Boron magnets, and also the encapsulation method used to fasten them to the shaft, the SME motors can achieve very high acceleration and withstand high overloads without risk of demagnetisation or detachment of the magnets.

Specific applications for the SME Series include all types especially those for the packaging and handling industry, and all those applications where very high dynamic performances and very low inertias are required.

### Features

- Single Cable solution (Hiperface DSL® feedback)
- Further Feedback support:  
Resolver, Hiperface and EnDat interface,  
Hall sensors, rotary and linear encoders
- Customised windings/voltages
- Increased Inertia option
- Multiple connection options

### Application

- Packaging Machinery
- Food & Beverage
- Pharma
- Material Handling
- Material Forming
- Factory Automation
- In-Plant Automotive
- Robotics
- Printing
- Servo Hydraulic Pumps



### Technical Characteristics - Overview

<b>Motor Type</b>	Permanent magnets synchronous servomotor
<b>Rotor Design</b>	Rotor with surface rare earth magnets
<b>Power Range</b>	0.2...5.3 kW
<b>Torque Range</b>	0.35...17 Nm
<b>Speed Range</b>	0...7500 min <sup>-1</sup>
<b>Mounting</b>	Flange with smooth holes
<b>Shaft End</b>	Plain keyed shaft Plain smooth shaft (option)
<b>Cooling</b>	Natural ventilation
<b>Protection Level (IEC60034-5)</b>	IP64 IP65 (option)
<b>Feedback sensor</b>	Encoder Hiperface DSL® (option S5, S6)
<b>Other options</b>	Brake Thermal protection (PTC) Increased inertia
<b>Marking</b>	CE / UL
<b>Voltage Supply</b>	230 / 400 VAC other voltage under request
<b>Temperature Class</b>	Class F
<b>Connections</b>	Single rotatable connector

# Technical Characteristics

## Technical Characteristics\*

### 230 VAC supply voltage

Model	Size	Stall <sup>(1)</sup>		Nominal <sup>(1)</sup>			Peak <sup>(1)</sup> Torque	Inertia		Ke <sup>(2) (3)</sup>	Kt <sup>(2) (3)</sup>
		Torque	Current	Torque	Speed	Current		No brake	With brake		
		T <sub>065</sub> (T <sub>105</sub> ) [Nm]	I <sub>065</sub> [A]	T <sub>065</sub> [Nm]	n [min <sup>-1</sup> ]	I <sub>065</sub> [A]		T <sub>max</sub> [Nm]	J [kgmm <sup>2</sup> ]	J [kgmm <sup>2</sup> ]	
SM_60 30 0.55	60	0.55 (0.68)	0.7	0.50	3000	0.66	1.7	18	30.5	0.44	0.76
SM_60 45 0.55			1.0	0.39	4500	0.74				0.30	0.53
SM_60 60 0.55			1.4	0.24	6000	0.60				0.23	0.40
SM_60 16 1.4		1.4 (1.7)	0.95	1.35	1600	0.91	4.4	30	42.5	0.85	1.48
SM_60 30 1.4			1.73	1.20	3000	1.50				0.47	0.81
SM_60 45 1.4			2.37	1.00	4500	1.69				0.34	0.59
SM_60 60 1.4			2.98	0.80	6000	1.70				0.27	0.47
SM_60 75 1.4			3.85	0.15	7500	0.41				0.21	0.36
SM_82 10 03	82	3 (3.7)	1.2	2.9	1000	1.2	9	140	183	1.43	2.48
SM_82 16 03			1.8	2.9	1600	1.7				0.96	1.66
SM_82 30 03			3.1	2.7	3000	2.8				0.55	0.96
SM_82 33 03			3.5	2.4	3300	2.8				0.49	0.85
SM_82 45 03			4.7	2.2	4500	3.4				0.37	0.64
SM_82 60 03			6.1	1.5	6000	3.1				0.28	0.49
SM_82 75 03			7.5	0.6	7500	1.6				0.23	0.40
SM_100 16 06	100	6 (9)	3.7	5.8	1600	3.6	18	336	440	0.92	1.60
SM_100 30 06			5.9	5.0	3000	4.9				0.59	1.02
SM_100 45 06			9.4	3.5	4500	5.5				0.37	0.64
SM_100 55 06			11.8	2.6	5500	5.1				0.29	0.51
SM_100 75 06			14.7	0.6	7500	1.5				0.24	0.41
SM_115 16 10	115	10 (12.5)	6.0	9.0	1600	5.4	32	900	1000	0.96	1.66
SM_115 30 10			10.5	8.0	3000	8.4				0.55	0.95
SM_115 40 10			14.7	7.6	4000	11.2				0.39	0.68
SM_115 54 10			18.2	7.1	5400	12.9				0.32	0.55
SM_142 18 15	142	15 (19)	9.7	13.3	1800	8.6	47	1400	1600	0.89	1.54
SM_142 30 15			16.0	12.5	3000	13.4				0.54	0.94

\* Data referred only to Single Cable Servo Motor System

<sup>(1)</sup> Data referred to motor mounted on a steel flange in horizontal position with dim. 200x230x20 mm (for SM\_60,82), dim. 200x270x20 mm (for SM\_100,115,142). Stall torques refer to motor turning at 100 min<sup>-1</sup>

<sup>(2)</sup> Data measured at 20 °C. When "hot" consider 5 % derating

<sup>(3)</sup> Tollerance data ±10 %

## 400 VAC power supply

Model	Size	Stall <sup>(1)</sup>		Nominal <sup>(1)</sup>			Peak <sup>(1)</sup> Torque	Inertia		Ke <sup>(2) (3)</sup>	Kt <sup>(2) (3)</sup>
		Torque	Current	Torque	Speed	Current		No brake	With brake		
		T <sub>065</sub> (T <sub>100</sub> ) [Nm]	I <sub>065</sub> [A]	T <sub>n065</sub> [Nm]	n [min <sup>-1</sup> ]	I <sub>n065</sub> [A]		J [kgmm <sup>2</sup> ]	J [kgmm <sup>2</sup> ]		
SM_60 30 1.4	60	1.4 (1.7)	0.95	1.2	3000	0.81	4.4	30	42.5	0.81	1.48
SM_60 45 1.4			1.37	1.0	4500	0.98				0.59	1.02
SM_60 60 1.4			1.73	0.8	6000	0.99				0.68	0.81
SM_60 75 1.4			2.15	0.15	7500	0.23				0.38	0.65
SM_82 30 03	82	3 (3.7)	1.8	2.7	3000	1.6	9	140	183	0.96	1.66
SM_82 45 03			2.7	2.2	4500	2.0				0.64	1.11
SM_82 56 03			3.1	1.6	5600	1.7				0.55	0.96
SM_82 60 03			3.5	1.7	6000	2.0				0.49	0.85
SM_82 75 03			4.4	0.6	7500	0.9				0.39	0.68
SM_100 30 06	100	6 (9)	3.7	5.0	3000	3.1	18	336	440	0.92	1.60
SM_100 45 06			5.6	3.5	4500	3.3				0.62	1.07
SM_100 56 06			5.9	2.5	5600	2.4				0.59	1.02
SM_100 75 06			9.4	0.6	7500	0.9				0.37	0.64
SM_115 20 10	115	10 (12.5)	4.5	9.0	2000	4.06	32	900	1000	1.28	2.22
SM_115 30 10			6.0	8.0	3000	4.82				0.96	1.66
SM_115 40 10			8.0	7.6	4000	6.05				0.73	1.26
SM_115 56 10			10.5	6.0	5600	6.30				0.55	0.95
SM_142 20 15	142	15 (19)	6.4	13.0	2000	5.5	47	1400	1600	1.36	2.35
SM_142 30 15			9.7	12.5	3000	8.1				0.89	1.54
SM_142 45 15			14.4	10.9	4500	10.5				0.60	1.04
SM_142 56 15			16.0	9.2	5600	9.8				0.54	0.94
SM_170 10 36	170		available on request								
SM_170 27 36											

<sup>(1)</sup> Data referred to motor mounted on a steel flange in horizontal position with dim. 200x230x20 mm (for SM\_60,82), dim. 200x270x20 mm (for SM\_100,115,142). Stall torques refer to motor turning at 100 min<sup>-1</sup>

<sup>(2)</sup> Data measured at 20 °C. When "hot" consider 5 % derating

<sup>(3)</sup> Tollerance data ±10 %

## STANDARDS

**In compliance with:** 73/23/CEE and 93/68/CEE

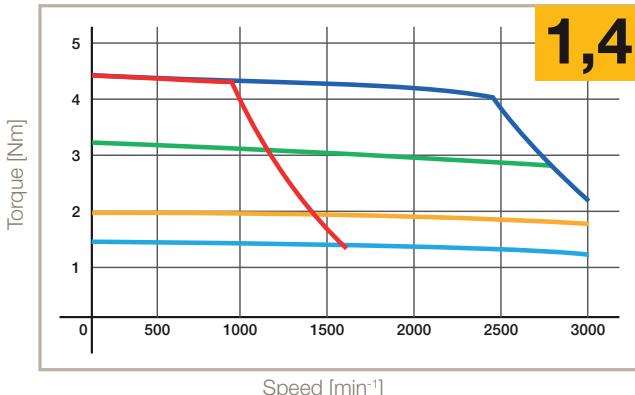
- EN60034-1
- EN60034-5
- EN60034-5/A1
- EN60034-9
- EN60034-14

Marked  

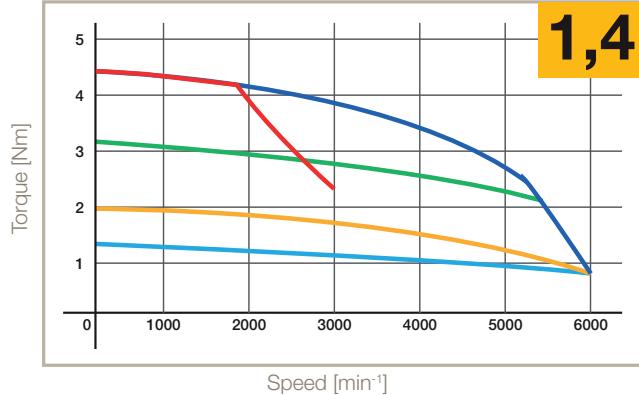
## Speed Torque Curves

### SME60

1600 min<sup>-1</sup> 230 V - 3000 min<sup>-1</sup> 400 V

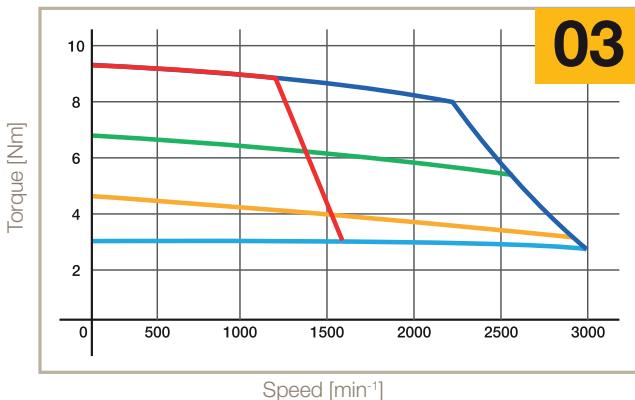


3000 min<sup>-1</sup> 230 V - 6000 min<sup>-1</sup> 400 V

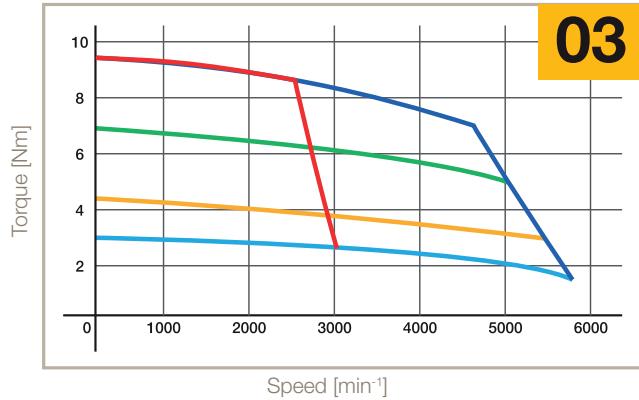


### SME82

1600 min<sup>-1</sup> 230 V - 3000 min<sup>-1</sup> 400 V

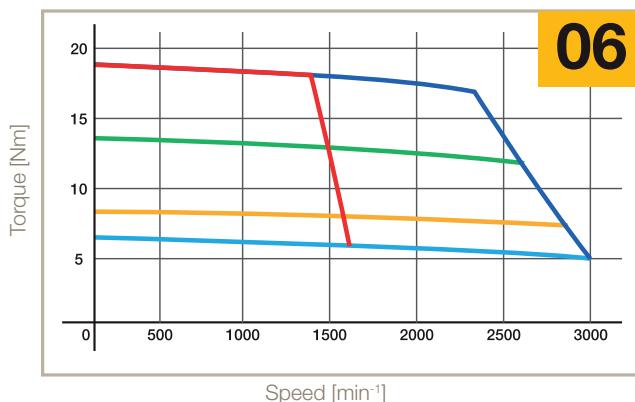


3000 min<sup>-1</sup> 230 V - 5600 min<sup>-1</sup> 400 V

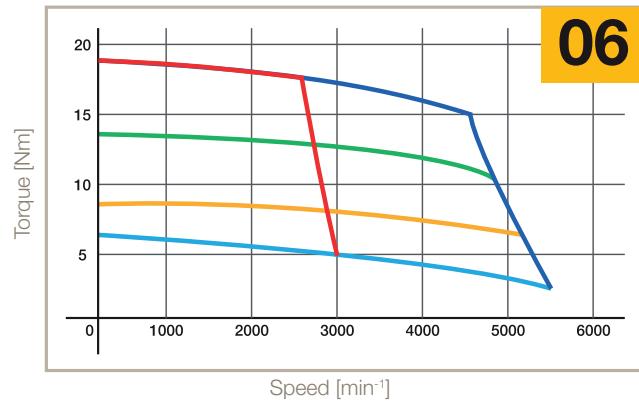


### SME100

1600 min<sup>-1</sup> 230 V - 3000 min<sup>-1</sup> 400 V



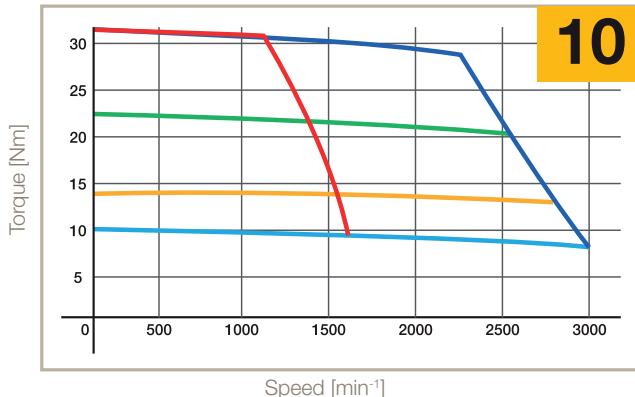
3000 min<sup>-1</sup> 230 V - 5600 min<sup>-1</sup> 400 V



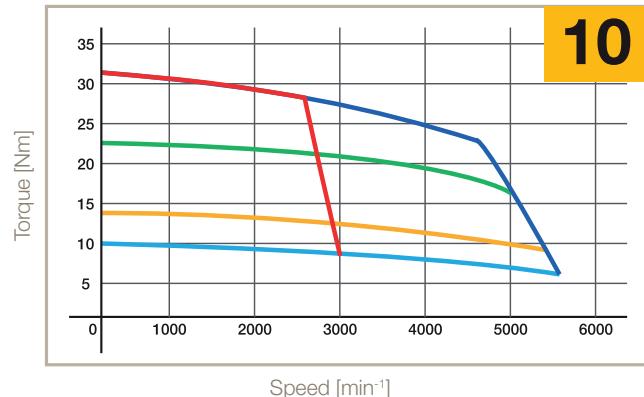
Legend:  
 — S1 65 K, ΔT  
 — S3 10 %, 5 min, 230 V  
 — S3 10 %, 5 min, 400 V  
 — S3 50 %, 5 min  
 — S3 20 %, 5 min

### SME115

**1600 min<sup>-1</sup> 230 V - 3000 min<sup>-1</sup> 400 V**

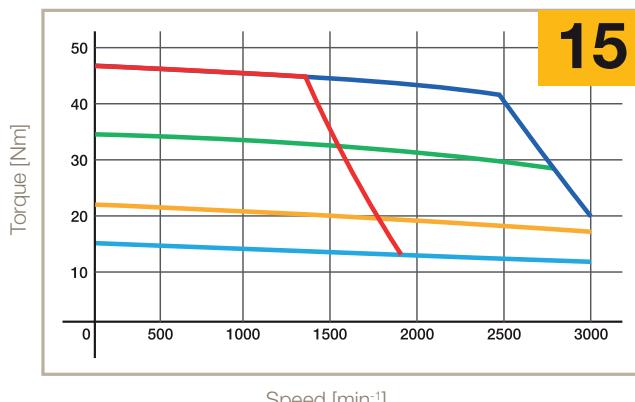


**3000 min<sup>-1</sup> 230 V - 5600 min<sup>-1</sup> 400 V**

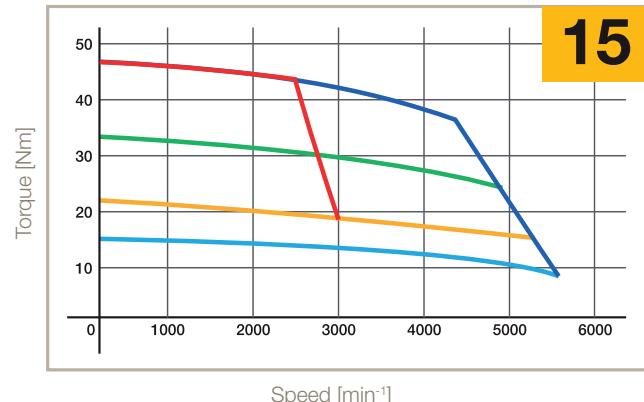


### SME142

**1800 min<sup>-1</sup> 230 V - 3000 min<sup>-1</sup> 400 V**



**3000 min<sup>-1</sup> 230 V - 5600 min<sup>-1</sup> 400 V**

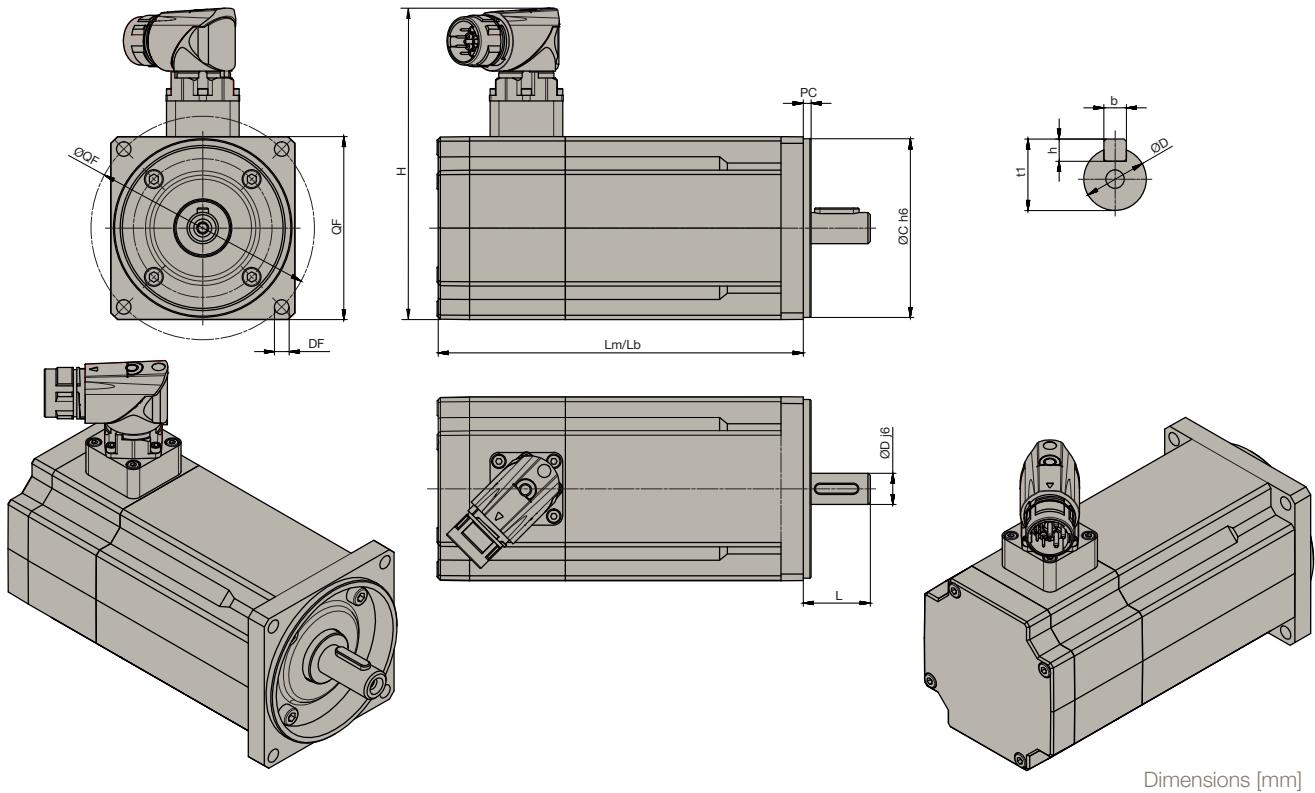


— S1 65 K,  $\Delta T$   
— S3 10 %, 5 min, 400 V  
— S3 50 %, 5 min

— S3 10 %, 5 min, 230 V  
— S3 50 %, 5 min  
— S3 20 %, 5 min

Single Cable Servo Drive System  
Low Inertia Servo Motors - SME - Technical Characteristics

## Dimensions



Dimensions [mm]

Motors Size		LM LB	Weight [kg]	DxL	b <h></h>	t1	VxZ	H	C	F	DF	G	PC	QF	Order Code QF
SME	60	0.55	88 137	- 1	9x20 11x23	3x3 4x4	10.2 12.5	- M4x10	111.5	40	63	5.5	74	-	60 8
		1.4	129.5 161	1.5	9x20 11x23	3x3 4x4	10.2 12.5	M4x10		60	75	6	90	2.5	70 5
		0.55	159 202	3.6	11x23 <sup>(2)</sup> 14x30	4x4	12.5	M4x12		40	63	5.5	74	2.5	60 8
		1.4	163.5 206.5	3.6	11x23 <sup>(2)</sup> 14x30 19x40 <sup>(1)</sup>	5x5 6x6	16 21.5	M4x12 M5x12.5 M6x16		60	75	6	90	2.5	70 5
	82	0.55	191.5 238.5	4.7	19x40 24x50	6x6 8x7	21.5 27	M6x16 M8x19	140	60	75	6	90	3.5	70 7
		1.4	220 265	3.6	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		80	100	6.5	112	3.5	82 8
		0.6	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		95	115	9	135	3.5	100 5
	100	0.6	191.5 238.5	4.7	19x40 24x50	6x6 8x7	21.5 27	M6x16 M8x19	157.5	80	100	7	135	3.5	100 8
		1.4	220 265	3.6	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		95	115	9	135	3.5	100 5
		0.6	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		95	115	9	156	3.5	115 9
		1.4	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		95	130	9	156	3.5	115 8
	115	0.6	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22	172	110	130	9	156	3.5	130 7
		1.4	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		130	165	11	196.5	3.5	145 5
		0.6	243 293	4.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22		199	130	165	11	192.5	3.5
	142	1.5	243 293	13	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22							

**LM:** motor's lenght without brake and with resolver

**LB:** motor's lenght with brake and resolver

**DxL:** Shaft

**b**: Key

**T1:** Overall shaft height

**VxZ:** Shaft hole depth

**H:** height

**C:** Center

**DF:** Fixing holes

**QF:** Mounting flange

**F:** Pitch circle diameter

**G:** Diagonal Dimension

**PC:** Centre Depth

<sup>(1)</sup> not available with flange 7

<sup>(2)</sup> only for torque <2 Nm

## Options

Parker SME family motors are available with standard and custom options to adapt motor on your application.  
If the option for your application is not listed, please consult our technical department.

### Holding Brake

All SME motors are available with option holding brake.

The fail-safe (supply voltage 24 VDC  $\pm 10\%$ ) holding brake is incorporated in the motor at the opposite side of the front flange and is applied when there is no voltage present. Because of the power loss caused by the brake, torque values must be reduced by 5 %. The holding brakes shall be used with the motor at a standstill and not for dynamic braking. For normal uses, they are maintenance free brakes.

Motor	Voltage [V]	Current [A]	Torque @20 °C [Nm]	Added Length [mm]	Added Weight [kg]	Added Inertia [kgmm²]
SME60	24	0.34	2.2	31.5	0.3	12.5
SME82	24	0.5	5	45.5	0.7	43
SME100	24	0.67	11	47	0.6	104
SME115	24	0.67	11	45	2	100
SME142	24	0.75	22	50	3	200

### Hiperface DSL® Feedback

SME (one cable) motors are available with encoder Hiperface DSL® feedback, with two different typology:

- Hiperface DSL® absolute encoder Single Turn
- Hiperface DSL® encoder Multi Turn

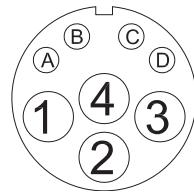
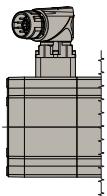
Code	S5	S6
Type		
Turn	Single	Multi
Resolution per revolutions		
Available memory space		
Positions per revolutions		
Distinguishable revolutions	1	4096
System accuracy differential	$\pm 40''$	
Power supply	7...12 VDC	
Max. speed [min⁻¹]	6000	
Temperature	-20°C...+105°C	
Safety integrity level	SIL2 (IEC 61508), SILCL2 (IEC 62061)	

### Medium Inertia

Where the application needs different values of inertia, SME can provide a standard adder.

Motor	Added inertia [kgmm²]	Added length [mm]	Added weight [kg]
SME60	29	31.5	0.32
SME82	270	43	0.91
SME100	284	47	0.68
SME115	900	45	2.28
SME142	690	50	2.49

## Layout and Connectors



	Hiperface DSL® Connector (IZ)
SME60	Yes
SME82	Yes
SME100	Yes
SME115	Yes
SME142	Yes

Pin	
1	U
2	GND
3	V
4	W
A	Brake +
B	Brake -
C	Signal +
D	Signal -

## Association Motors/Drives

### 230 VAC Supply Voltage

Motor	Rated Speed [min <sup>-1</sup> ]	Stall Current [A]	TPD-M
<b>230 VAC supply voltage</b>			
SME60 30 0.55	3000	0.7	TPD-M02...
SME60 45 0.55	4500	1	TPD-M02...
SME60 60 0.55	6000	1.4	TPD-M02...
SME60 16 1.4	1600	0.95	TPD-M02...
SME60 30 1.4	3000	1.73	TPD-M02...
SME60 45 1.4	4500	2.37	TPD-M05...
SME60 60 1.4	6000	2.98	TPD-M05...
SME60 75 1.4	7500	3.85	TPD-M05...
SME82 10 03	1000	1.2	TPD-M02...
SME82 16 03	1600	1.8	TPD-M02...
SME82 30 03	3000	3.1	TPD-M05...
SME82 33 03	3300	3.5	TPD-M05...
SME82 45 03	4500	4.7	TPD-M05...
SME82 60 03	6000	6.1	TPD-M08...
SME82 75 03	7500	7.5	TPD-M08...
SME100 16 06	1600	3.7	TPD-M05...
SME100 30 06	3000	5.9	TPD-M08...
SME100 45 06	4500	9.4	TPD-M10...
SME100 55 06	5500	11.8	TPD-M15...
SME100 75 06	7500	14.7	TPD-M15...
SME115 16 10	1600	6	TPD-M08...
SME115 30 10	3000	10.5	TPD-M10...
SME115 40 10	4000	14.7	TPD-M15...
SME115 54 10	5400	18.2	TPD-M30...
SME142 18 15	1800	9.7	TPD-M10...
SME142 30 15	3000	16	TPD-M30...

### 400 VAC Supply Voltage

Motor	Rated Speed [min <sup>-1</sup> ]	Stall Current [A]	TPD-M
<b>400 VAC supply voltage</b>			
SME60 30 1.4	3000	0.95	TPD-M02..
SME60 45 1.4	4500	1.37	TPD-M02..
SME60 60 1.4	6000	1.73	TPD-M02..
SME60 75 1.4	7500	2.15	TPD-M05..
SME82 30 03	3000	1.8	TPD-M02..
SME82 45 03	4500	2.7	TPD-M05..
SME82 56 03	5600	3.1	TPD-M05..
SME82 60 03	6000	3.5	TPD-M05..
SME82 75 03	7500	4.4	TPD-M05..
SME100 30 06	3000	3.7	TPD-M05..
SME100 45 06	4500	5.6	TPD-M08..
SME100 56 06	5600	5.9	TPD-M08..
SME115 20 10	2000	4.5	TPD-M05..
SME115 30 10	3000	6.0	TPD-M08..
SME115 40 10	4000	8.0	TPD-M08..
SME115 56 10	5600	10.5	TPD-M15..
SME142 20 15	2000	6.4	TPD-M08..
SME142 30 15	3000	9.7	TPD-M10..
SME142 45 15	4500	14.4	TPD-M15..
SME142 56 15	5600	16	TPD-M30..

# Order Code

## Motor Series SME

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Order example	SME	A	60	30	1.4	5	11	IZ		64	S6		M		2	

<b>1 Type Of Motor (mandatory field)</b>	<b>10 Female connectors option</b>
<b>SME</b> Standard Motor with Encoder	With Female / flying connectors (empty field)
<b>2 Brake Option</b>	<b>W</b> Without Female / flying connectors
No Brake Option (empty field)	
<b>A</b> Motor with Holding Brake (brakes when the supply voltage is 0)	
<b>3 Motor Frame Size (mandatory field)</b>	<b>11 Protection Degree (mandatory field)</b>
<b>60</b> Torque range 0,55...1.4 Nm	<b>64</b> IP64
<b>82</b> Torque 3 Nm	<b>65</b> IP65
<b>100</b> Torque range 6 Nm	<b>12 Feedback</b>
<b>115</b> Torque range 10 Nm	<b>S5</b> 32768spr Single Turn Hiperface DSL® Encoder Feedback SIL2
<b>142</b> Torque range 15...17 Nm	<b>S6</b> 32768spr x 4096 Multi Turn Hiperface DSL® Encoder Feedback SIL2
<b>170</b> Torque range 36...60 Nm (Provisional data)	<b>13 Option Resolver</b>
<b>4 Winding (mandatory field)</b>	Standard Resolver (empty field)
<b>nn</b> min⁻¹ (x100)	<b>14 Option Inertia</b>
<b>5 Motor Torque (mandatory field)</b>	Standard Inertia (empty field)
<b>nn</b> Torque [Nm]	<b>M</b> Medium Inertia available without selected A in field 2
<b>6 Flange (mandatory field)</b>	<b>15 Special Option</b>
<b>5</b> B5 Flange	No Special Option (empty field)
<b>7</b> Only for Frame 82 and 115	<b>1Bxx</b> Motor with 2-side output shaft, where xx is the diameter of second shaft
<b>8</b> Only for Frame 60, 82, 100 and 115	<b>16 Voltage</b>
<b>9</b> Only for Frame 115	<b>0A</b> 24 V
<b>A B C</b> Special Flange	<b>0B</b> 34 V
<b>7 Shaft (mandatory field)</b>	<b>0C</b> 48 V
<b>11</b> 11x23 mm for size 60	<b>0D</b> 50 V
<b>14</b> 14x30 mm for size 82	<b>0E</b> 60 V
<b>19</b> 19x40 mm for size 82/100/115/142	<b>0F</b> 72 V
<b>24</b> 24x50 mm for size 100/115/142	<b>0G</b> 74 V
<b>28</b> 28x60 mm for size 115/142	<b>0</b> 80 V
<b>A*</b> Special shaft under request	<b>0H</b> 96 V
<b>8 Key Shaft option</b>	<b>1A</b> 108-110 V
Shaft with Key (empty field)	<b>1D</b> 120 V
<b>S</b>	<b>1B</b> 125 V
Shaft without key	<b>1C</b> 150 V
<b>9 Layout - Connectors (mandatory field)</b>	<b>1</b> 180 V
<b>IZ</b> Single connector rotatable (Feedback included)	<b>2</b> 220-230 V
	<b>2A</b> 222 V
	<b>2B</b> 200 V
	<b>3</b> 330 V
	<b>4</b> 380-400 V
	<b>4A</b> 425 V
	<b>4C</b> 460 V
	<b>4B</b> 490 V

## Order Code

### Motor Cable for Hiperface DSL®

	1	2	3	4	5	6	7
Order example	CAVODSL	1,5x	3	PM-	TPD-	A00-	C

#### 1 Cable

**CAVODSL** Motor Cable for Single Cable Servo Drive System based on Hiperface DSL®

#### 2 Section [mm<sup>2</sup>]

**1,5x** 1,5 mm<sup>2</sup>

**2,5x** 2,5 mm<sup>2</sup>

4x, 6x, 10x, 25x 4 mm<sup>2</sup>, 6 mm<sup>2</sup>, 10 mm<sup>2</sup>, 25 mm<sup>2</sup>

#### 3 Length [m]

1, ... Length in metre (max. 50 m)

#### 4 Application Type

**PM-** Moving Application

#### 5 Drive Type

**TPD-** TPD Drive

#### 6 Option

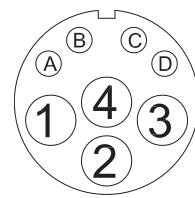
... Special customer drawing  
Internal table code

#### 7 Connector

**C** Mating connector  
Mating connector in the motor package

### Connector for Hiperface DSL®

Code	Description
<b>CONMOT2IZF</b>	Speedtec Female Connector
<b>CONMOT2IZM</b>	Speedtec Male Connector



# Triple Axis Servo Drive - TPD-M

## Product Overview

### Description

TPD-M is a multi axis drive system with each power module can supplying up to three servo motors. The base configuration consists of a common dc bus supply (PSU) and multiples TPD-M modules, connected through a common dc bus.

The modules are available as one, two or three axis versions, makings the system very flexible.

The TPD-M drive has been specifically designed for the Packaging OEM market but it can also be used in many other centralized automation structures which incorporate a large number of servo axes offering significant advantages.

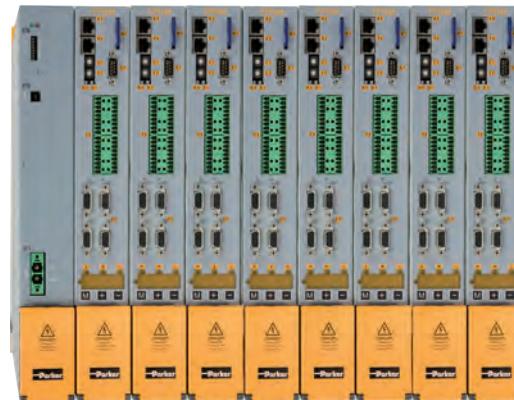
### Features

- New feedback system for single cable servo motors (Hiperface DSL®)  
Reduced cabling; only one cable connection between drive & motor
- The most compact multi-axis servo drive on the market
- Quick and simple wiring
- One, two or three axis versions combined in one housing
- Removable SD card
- Common DC bus connection for energy exchange between drives
- Further Feedback support:  
Resolver, Hiperface and EnDat interface, Hall sensors, rotary and linear encoders
- Fieldbus: CANopen - standard, EtherCAT - option

Motion control functionality is performed by means of EtherCAT Real Time CoE (CAN over Ethernet) communication, CAN / CANopen DS402 communication.

### Application

- Packaging Machinery
- Food & Beverage
- Material Handling
- Material Forming
- Factory Automation
- Robotics



### Technical Characteristics - Overview

TPD Axis	Continuos current [A <sub>rms</sub> ]	Peak current [A] ( $\leq 2$ s)
3 axis	2 + 2 + 2	4 + 4 + 4
	8 + 5 + 5	16 + 10 + 10
	2 + 2	4 + 4
2 axis	5 + 5	10 + 10
	8 + 8	16 + 16
	5/10/15/30	10/20/30/60
1 axis		

# Technical Characteristics

## Technical Characteristics

### TPD-M

Type	Unit	3 axis		
		2 + 2 + 2	8 + 5 + 5	
<b>Rated Output Current</b>	[A <sub>rms</sub> ]	2 + 2 + 2		8 + 5 + 5
<b>Peak Output Current (≤ 2 s)</b>	[A]	4 + 4 + 4		16 + 10 + 10
<b>Maximum Continuous Module Output Current</b>	[A]	6		16 <sup>(1)</sup>
<b>Maximum DC Voltage Supply</b>	[VDC]	750		

Type	Unit	2 axis			1 axis	
		2 + 2	5 + 5	8 + 8	15	30
<b>Rated Output Current</b>	[A <sub>rms</sub> ]	2 + 2	5 + 5	8 + 8	15	30
<b>Peak Output Current (≤ 2 s)</b>	[A]	4 + 4	10 + 10	16 + 16	30	60
<b>Maximum Continuous Module Output Current</b>	[A]	4	10	16	15	30
<b>Maximum DC Voltage Supply</b>	[VDC]	750				

<sup>(1)</sup> The max continuous module current is clamped to 16 A

## PSUP - Power Supply Unit

### Mains Supply

Power Supply Type	Unit	PSUP10			PSUP20			PSUP30 <sup>(2)</sup>		
<b>Input Voltage</b>		*230...480 VAC ±10 % 50...60 Hz (Rated voltage 3'400 VAC)								
<b>Output Voltage</b>		325...680 VDC ±10 %								
<b>Supplied Voltage</b>	[VAC]	230	400	480	230	400	480	230	400	480
<b>Output Power</b>	[kVA]	6	10	10	12	20	20	18	30	30
<b>Peak Output Power (&lt;5 s)</b>	[kVA]	12	20	20	24	40	40	34	60	60

### Control Supply

<b>Rated Input Voltage</b>		24 VDC ±10 %		
<b>Maximum Ripple</b>		1 V <sub>pkpk</sub>		
<b>Supply Current</b>	[A]	PSUP10D6: 0,2 A	PSUP20D6: 0,3 A	PSUP30D6: 0,3 A

<sup>(2)</sup> Operation of the PSUP30 only with line choke.

## Environmental Characteristics

Type	TPD-M	PSUP
<b>Operating Temperature</b>	0...+40 °C	
<b>Storage Temperature</b>	-25 °C...+55 °C	
<b>Shipping Temperature</b>	-25 °C...+70 °C	
<b>Product Enclosure Rating</b>	IP20 (only in closed electrical cabinet) UL open type equipment	
<b>Altitude</b>	1000 m ASL. Derate output current by 1.5 % per 100 m to a maximum of 2000 m	
<b>Operating Humidity</b>	Class 3K3 - Maximum 85 % non-condensing	
<b>Storage Humidity</b>	Class 1K3 - Maximum 95 % non-condensing	
<b>Shipping Humidity</b>	Class 2K3 - Maximum 95 % at 40 °C	
<b>Operating Vibration</b>	IEC60068-2-6 10...57 Hz width 0.075 mm 57...150 Hz accel. 9.81 m/s <sup>2</sup>	

## TPD-M Features

### Communication

- via USB port

### Networks and Bus Systems

- CANopen, 20...1000kbit/s, SDO1, PDO1...PDO4
- EtherCAT, 100Mbit/s, 1 cycle time
- Via Gateway
  - Profibus
  - DeviceNet

### Inputs / Outputs

- 4 digital input,
- 2 digital output,
- 1 analog input
- 1 analog output for each axes.
- 1 incremental encoder input,
- 1 incremental encoder output
- Additional I/O
  - 3 digital input 12bit,
  - 2 incremental encoder input,
  - 2 incremental encoder output
- Auxiliary Encoder
  - 1 in input for each axes
  - 1 in output

### Supported Feedback

- Encoder Hiperface DSL®

### Programming / Configuration

- PicoPLC
- MotionWiz with Oscilloscope function, real time and debugging features
- Removable SD card for
  - Software upgrades
  - Parameter storage
  - Application memory

### Technology Functions

- Torque control
- Speed control
- Position control
- Electronic gearbox
- Camming

### Safety Functions (STO)

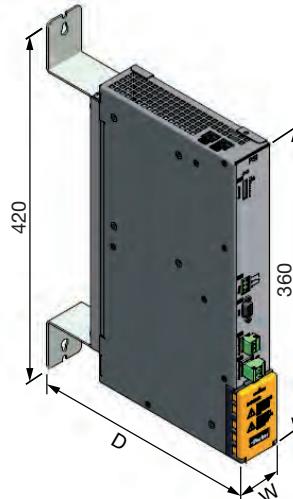
- 1 Safety Torque Off circuit for 3 axis module
- 2 independent Safety Torque Off circuit for 2 axis module
- 1 Safety Torque Off circuit for 1 axis module

## Standards & Conformance - EMC Compatibility

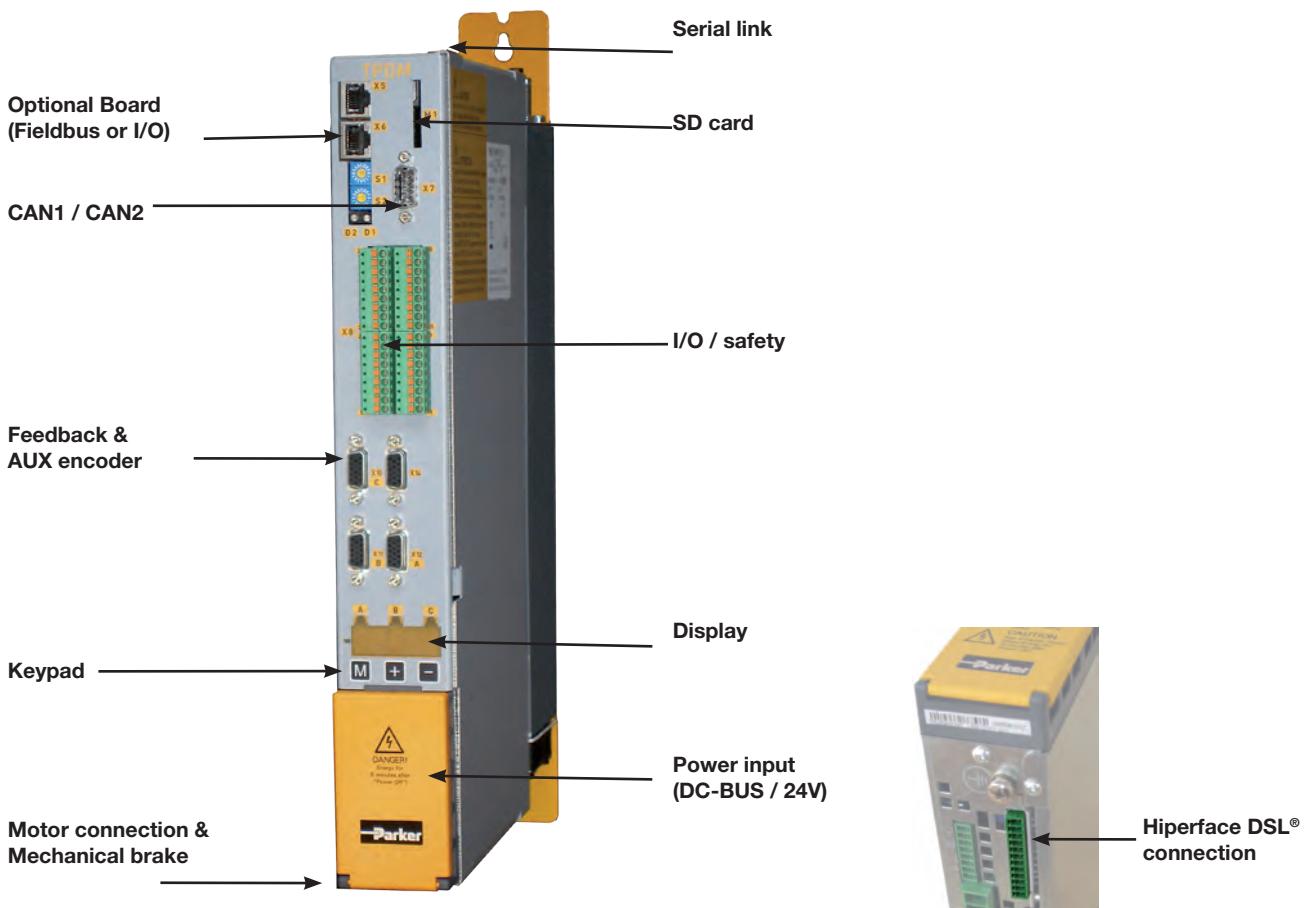
<b>2006/95/EC</b>	Low voltage directive
<b>EN 60204-1</b>	Safety of machinery - Electrical equipment of machines - Part 1: General requirements
<b>EN 61800-5-1</b>	Adjustable speed electrical power drive systems - safety requirements, thermal and energy
<b>UL508C</b>	(USA) Power Conversion Equipment
<b>2004/108/EC</b>	EMC directive
<b>EN 61800-3</b>	Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test method

## Dimensions

Type	W [mm]	D [mm]	Weight [kg]
<b>TPD-M 1/2/3 axes</b>	50	270	4.3
<b>TPD-M single axis 30 A</b>	100	270	8.6
<b>PSUP10</b>	50	270	3.6
<b>PSUP20 / PSUP30</b>	100	270	5.4



## Connector Layout



TPD-M bottom view

## Configuration Software - MotionWiz

MotionWiz is free of charge downloadable configuration software that allows users to configure and optimise the TPD-M series with a few easy clicks of the mouse.

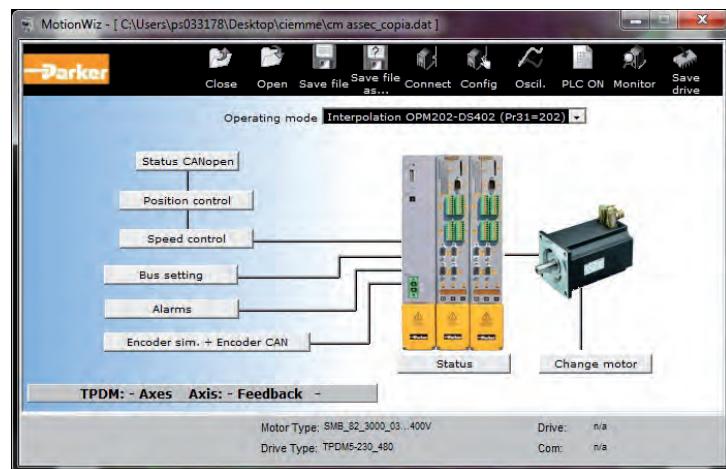
MotionWiz features an intuitive, easy and simple to use Windows® style environment to aid installation, optimisation and diagnostic use.

MotionWiz permits operation in both "on line" mode, directly in the controller, and in "offline" mode, remotely on the PC before downloading to the controller.

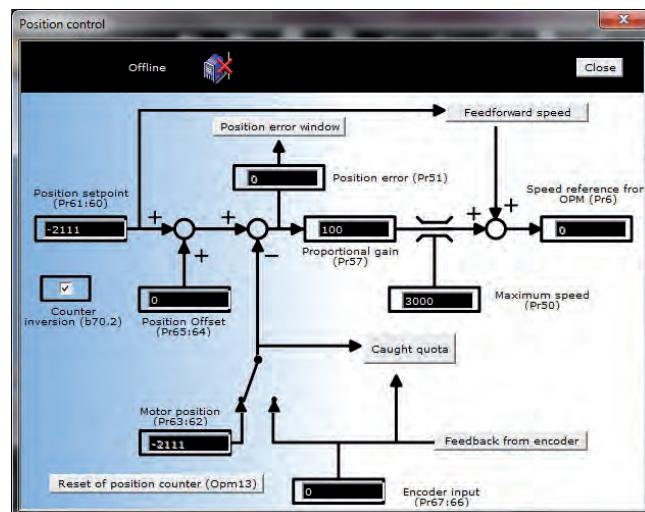
To simplify the configuration of systems with a large number of similar axes but with different motion profiles, MotionWiz allows users to copy the configuration from one application to another.

Inside the MotionWiz configurator is a database containing the technical characteristics of the full range of Parker motors and drives.

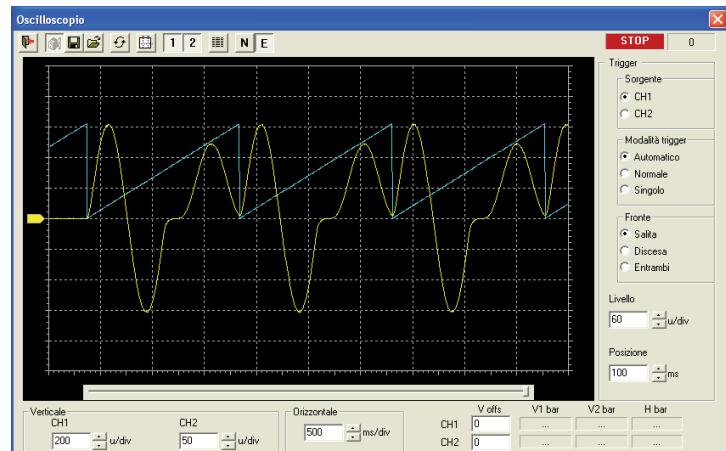
MotionWiz can be downloaded at [www.parker.com/eme/tpdm](http://www.parker.com/eme/tpdm)



MotionWiz: General settings



MotionWiz: Position control



MotionWiz Oscilloscope: Real speed & torque trends

## Order Code

### TPD-M System

	1	2	3	4	5	6	7
Order example	TPD	M	02 02 02	D	L	E5	G
<b>1 Drive Family</b>							
TPD Triple Power Drive							
<b>2 Axes</b>							
M Multi Axis							
<b>3 Drive Size</b>							
02 02 02 3 axis 2 A + 2 A + 2 A							
08 05 05 3 axis 8 A + 5 A + 5 A							
02 02 2 axis 2 A + 2 A							
05 05 2 axis 5 A + 5 A							
08 08 2 axis 8 A + 8 A							
5 single axis 5 A							
10 single axis 10 A							
15 single axis 15 A							
30 single axis 30 A							
<b>4 Fieldbus</b>							
D CANopen							
<b>5 Feedback system</b>							
Empty field Resolver							
E EnDat / Incremental / Sinc encoder							
H Incremental encoder + Hall sensors							
L DSL feedback							
<b>6 Option board</b>							
Empty field No option							
E5 EtherCAT option board							
E7 Analogic expansion board							
<b>7 Accessories</b>							
G Fixing shield							

### Mains module: PSUP

	1	2	3	4	5
Order example	PSU	P	10	D6	USB M00
<b>1 Device family</b>					
PSU Power module					
<b>2 Device type</b>					
P Power module					
<b>3 Nominal power; supply voltage</b>					
10 D6 10 kW; 400 VAC (3-phase)					
20 D6 20 kW; 400 VAC (3-phase)					
30 D6 30 kW; 400 VAC (3-phase) <sup>1)</sup>					
<b>4 Interface</b>					
USB USB connection					
<b>5 Options</b>					
M00 no additional supplement					

<sup>1)</sup> Operation of the PSUP30 only with line choke.

Required line choke for the PSUP30: 0.45 mH / 55 A

#### We offer the following line chokes:

LCG-0055-0.45 mH (WxDxH: 180 mmx140 mmx157 mm; 10 kg)

LCG-0055-0.45 mH-UL (with UL certification)

(WxDxH: 180 mmx170 mmx157 mm; 15 kg)

### Capacitor module

	1	2
Order example	PSC	023 M00

#### 1 Accessories

PSC Capacitor module

	2
Order example	023 M00
Type	23 µF no additional supplement
Type	47 µF no additional supplement
Type	68 µF no additional supplement

### Mains filter for PSUP

	1	2
Order example	NFI	03/01

#### 1 Accessories

NFI Mains filter

	2
Order example	03/01
Type	for PSUP10 Reference axis combination 3 x 480 V 25 A 6 x 10 m motor cable length
Type	for PSUP10 Reference axis combination 3 x 480 V 25 A 6 x 50 m motor cable length
Type	for PSUP20, PSUP30 Reference axis combination 3 x 480 V 50 A 6 x 50 m motor cable length

### Braking resistors

	1	2
Order example	BRM	05/01

#### 1 Accessories

BRM Braking resistor

	2
Order example	13/01
Type	30 Ω / 0.5 kW <sub>cont.</sub> for PSUP10D6, for PSUP20D6 (2x30Ω parallel)
Type	14/01 15 Ω / 0.5 kW <sub>cont.</sub> for PSUP10D6 (2 x 15 Ω in series) for PSUP20, PSUP30
Type	12/01 18 Ω / 4.5 kW <sub>cont.</sub> for PSUP30

### Motor output choke

For disturbance suppression when the motor connecting cables are long.

	1	2
Order example	MDR	01/04

#### 1 Accessories

MDR Motor output choke  
(for TPD-M >20 m motor cable)

	2
Order example	01/01
Type	up to 16 A rated motor current
Type	01/02 up to 30 A rated motor current
Type	01/04 up to 6.3 A rated motor current

### Other Accessories

Order Code	Description
Motionwiz	Programming Software
Exp-Ground	Fixing shield assembly
USBTODRIVE	USB to RS232/422 converter with cable

# Parker's Motion & Control Technologies

**At Parker, we're guided by a relentless drive to help our customers become more productive and achieve higher levels of profitability by engineering the best systems for their requirements. It means looking at customer applications from many angles to find new ways to create value. Whatever the motion and control technology need, Parker has the experience, breadth of product and global reach to consistently deliver. No company knows more about motion and control technology than Parker. For further info call 00800 27 27 5374.**



## AEROSPACE

### Key Markets

- Aircraft engines
- Business & general aviation
- Commercial transports
- Land-based weapons systems
- Military aircraft
- Missiles & launch vehicles
- Regional transports
- Unmanned aerial vehicles

### Key Products

- Flight control systems & components
- Fluid conveyance systems
- Fluid metering delivery & atomization devices
- Fuel systems & components
- Hydraulic systems & components
- Inert nitrogen generating systems
- Pneumatic systems & components
- Wheels & brakes



## CLIMATE CONTROL

### Key Markets

- Agriculture
- Air conditioning
- Food, beverage & dairy
- Life sciences & medical
- Precision cooling
- Processing
- Transportation

### Key Products

- CO<sub>2</sub> controls
- Electronic controllers
- Filter driers
- Hand shut-off valves
- Hose & fittings
- Pressure regulating valves
- Refrigerant distributors
- Safety relief valves
- Solenoid valves
- Thermostatic expansion valves



## ELECTROMECHANICAL

### Key Markets

- Aerospace
- Factory automation
- Food & beverage
- Life science & medical
- Machine tools
- Packaging machinery
- Paper machinery
- Plastics machinery & converting
- Primary metals
- Semiconductor & electronics
- Textile
- Wire & cable

### Key Products

- AC/DC drives & systems
- Electric actuators
- Controllers
- Gantry robots
- Gearheads
- Human machine interfaces
- Industrial PCs
- Inverters
- Linear motors, slides and stages
- Precision stages
- Stepper motors
- Servo motors, drives & controls
- Structural extrusions



## FILTRATION

### Key Markets

- Food & beverage
- Industrial machinery
- Life sciences
- Marine
- Mobile equipment
- Oil & gas
- Power generation
- Process
- Transportation

### Key Products

- Analytical gas generators
- Compressed air & gas filters
- Condition monitoring
- Engine air, fuel & oil filtration & systems
- Hydraulic, lubrication & coolant filters
- Process, chemical, water & microfiltration filters
- Nitrogen, hydrogen & zero air generators



## FLUID & GAS HANDLING

### Key Markets

- Aerospace
- Agriculture
- Bulk chemical handling
- Construction machinery
- Food & beverage
- Fuel & gas delivery
- Industrial machinery
- Mobile
- Oil & gas
- Transportation
- Welding

### Key Products

- Brass fittings & valves
- Diagnostic equipment
- Fluid conveyance systems
- Industrial hose
- PTFE & PFA hose, tubing & plastic fittings
- Rubber & thermoplastic hose & couplings
- Tube fittings & adapters
- Quick disconnects



## HYDRAULICS

### Key Markets

- Aerospace
- Aerial lift
- Agriculture
- Construction machinery
- Forestry
- Industrial machinery
- Mining
- Oil & gas
- Power generation & energy
- Truck hydraulics

### Key Products

- Diagnostic equipment
- Hydraulic cylinders & accumulators
- Hydraulic motors & pumps
- Hydraulic systems
- Hydraulic valves & controls
- Power take-offs
- Rubber & thermoplastic hose & couplings
- Tube fittings & adapters
- Quick disconnects



## PNEUMATICS

### Key Markets

- Aerospace
- Conveyor & material handling
- Factory automation
- Food & beverage
- Life science & medical
- Machine tools
- Packaging machinery
- Transportation & automotive

### Key Products

- Air preparation
- Compact cylinders
- Field bus valve systems
- Grippers
- Guided cylinders
- Manifolds
- Miniature fluidics
- Pneumatic accessories
- Pneumatic actuators & grippers
- Pneumatic valves and controls
- Rodless cylinders
- Rotary actuators
- Tie rod cylinders
- Vacuum generators, cups & sensors



## PROCESS CONTROL

### Key Markets

- Chemical & refining
- Food, beverage & dairy
- Medical & dental
- Microelectronics
- Oil & gas
- Power generation

### Key Products

- Analytical sample conditioning products & systems
- Fluoropolymer chemical delivery fittings, valves & pumps
- High purity gas delivery fittings, valves & regulators
- Instrumentation fittings, valves & regulators
- Medium pressure fittings & valves
- Process control manifolds



## SEALING & SHIELDING

### Key Markets

- Aerospace
- Chemical processing
- Consumer
- Energy, oil & gas
- Fluid power
- General industrial
- Information technology
- Life sciences
- Military
- Semiconductor
- Telecommunications
- Transportation

### Key Products

- Dynamic seals
- Elastomeric o-rings
- EMI shielding
- Extruded & precision-cut, fabricated elastomeric seals
- Homogeneous & inserted elastomeric shapes
- High temperature metal seals
- Metal & plastic retained composite seals
- Thermal management

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